FINAL REPORT

Electrical Engineering (ESE 498)

Senior Design Project

Plug and Play Engine Sound Replicator

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# Abstract

This project was brought to the department by a third party member, Larry Heugatter, who noticed spark plug interference noise on his car radio that increased when he accelerated. He conceived a device which would use this noise to generate engine sounds of a super car in sync with the car being driven.

While spark plug noise was not a viable option of sensing RPM, two alternate methods were found. The first was alternator noise on the car adapter plug, an analog signal that can be processed into a digital signal. The second was the OBD‐II plug, available in most cars, that communicates on a digital serial protocol.

Experimentation with sound files produced a groundwork for determining how many files of what size are necessary to produce a clean and realistic sound, as well as an idea of the memory and processing power that would be required. In the future, the individual components will need to be integrated into a system that does not require a laptop to process. Other issues to explore are making the system wireless to avoid wire tangles, legal issues with using engine sounds, and the question of distraction.

# Introduction

The motivation behind our project was that many people wish to drive fast cars like Ferraris and Lamborghinis, due to their stunning looks, incredible speed, and harmonious sound. Currently there are options on the market for people to modify their everyday cars, including the use of expensive body kits, engine upgrades, or exhaust replacements for those who can’t afford such vehicles.

However, such modifications require time, money, and automotive experience.

With the inspiration from Larry Heugatter, our project began as an idea to bring the glorious sound of six‐figure super cars to everyday people with common cars, without the automotive experience or intense modifications. Our goal was to find a quick, easy, and inexpensive way to give a mundane car the sound of a fire‐breathing supercar.

In undertaking this project, there were three major tasks to accomplish. First, we needed to find a way to monitor a car’s RPM and then convert the analog output into a digital signal for processing. Second given a signal to process, there was the task of matching the RPM sounds of a difference car to create the sound effect of driving a high performance car. Lastly, when these two technical tasks were completed there would be an actual device that connects to the car, receives power, and emits sound either through a speaker or through the vehicle’s built in audio system.

# Project Priorities

The project can be divided into several tasks. We decided to focus our work on the individual components at the expense of working to combine them into a functioning prototype device. We felt using computers to handle processing and communication rather than dedicated hardware would make the project more manageable in the time allotted.

The first step was determining the current state of the car’s engine, so that engine sounds could be matched to it. Because noise experienced by the driver is most closely correlated with the rate of the engine firing, or revolutions per minute (RPM), we sought to detect the RPM in a way that would fulfill the project criteria. This portion of the project required the majority of our research and experimentation, and was therefore a top priority of the project.

Second was processing the RPM reading into a useful signal. Tested methods for sensing RPM would yield either digital and analog signals. In the case of digital signals, processing involves a well‐documented communication protocol. In the case of analog signals, conventional filtering and converting components are available as discrete components. As shown, processing can be done in a straight‐forward manner and was therefore not given as much priority as sensing.

Lastly was the problem of synthesizing sounds to correlate with the processed signal. This involves a system to select a sound file to play based on the input signal and a delivery system for the audio. Because of the aforementioned de‐emphasis on interfacing components, most of this work focused on determining how to efficiently

achieve good sound, determining the minimum resolution of sound files and focusing on a delivery system.

# Sensing RPM

## Criteria

The design for sensing the car’s rpm conforms to the following standards:

* The design should be nearly universal. The sensing method/hardware should be compatible with as many vehicles as possible, either correcting for differences between different models and makes, or relying only on components and characteristics that are nearly universal.
* The design should be “Plug‐and‐Play”. The sensing hardware should be installed easily with few, or ideally no, tools. Removal should be similarly easy. The installation should not involve opening any panels or getting under the hood: any parts should be confined to the car’s interior.
* Installation and operation should not require extensive automotive knowledge.

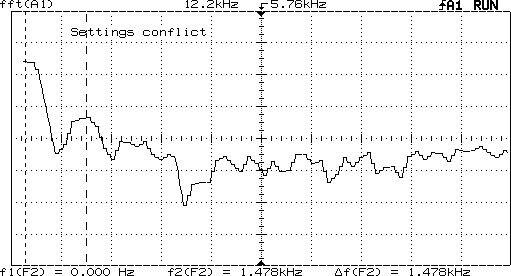
## Car Adapter Plug

The car adaptor plug, or cigarette lighter plug, is one of the two viable methods for remotely sensing the vehicle’s RPM. The plug is often used as a 12V DC power supply for small devices (phones, PDAs, etc.). Since the battery is connected do the alternator for charging, it experiences noise from the alternator’s rectifier circuit when the engine

is running.

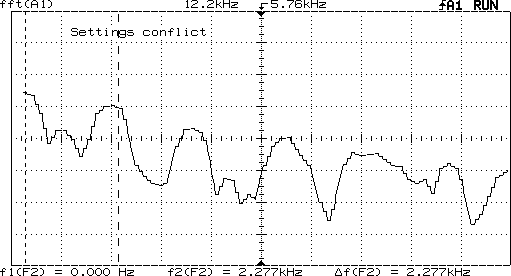
Measuring RPM through the noise from the alternator through the car adapter plug meets the criteria established in the previous section. While automotive electrical systems have become more advanced and better at filtering noise, it is never entirely erased, and usually correlates with filtering from the cord/device end. Therefore, we believe alternator noise has the potential to be measured form most cars. Furthermore, a car adapter plug is easy to install and uninstall, requiring no more automotive knowledge than installing and uninstalling a car charger for a cell phone.

Fourier analysis of the adaptor plug signal at different engine RPM is shown in Figure 1, Figure 2, and Figure 3 with the frequency of interest highlighted.



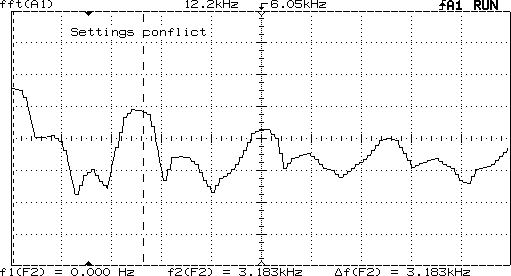
1.48 kHz

Figure 1: Fast Fourier Analysis of Plug Signal at Approximately 1000 RPM



2.27 kHz

Figure 2: Fast Fourier Analysis of Plug Signal at Approximately 1500 RPM



3.18 kHz

Figure 3: Fast Fourier Analysis of Plug Signal at Approximately 2000 RPM Aside from the DC component, there is a strong component that moves from 950Hz at idle (approximately 500 RPM) to 3.18kHz at 2000 RPM. The frequency of this component correlates linearly to RPM over the range tested, where:

RPM=0.64\*frequency

## OBD­II Connector

The OBD‐II (On‐Board Diagnosis Connector) is a standardized connector, shown in Figure 4, required on vehicles sold in America for all models after 1996. The system can both store data, and provide real‐time read outs for various engine information such as engine temperature, speed, error codes, and RPM. Several different standards exist for the OBD‐II, outlined in Table 1. Model years 2009 and later will all use the CAN standard.

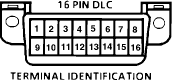


Figure 4: Pin Layout of OBD‐II Connector

|  |  |  |
| --- | --- | --- |
| **Pin Usage on OBD-II Port by Standard** | | |
| **Standard** | **Usage** | **Pins used** |
| Pulse Width Modulation | Ford | 2,4,10,16 |
| Variable Pulse width | Chevy | 2,4,16 |
| ISO 9141-2 | European and Asian  Models | 4,7,15,16 |
| KWP200 |  | 4,7,15,16 |
| CAN | Mandatory Standard  for 2009 and beyond | 4,6,14,16 |

Table 1: Pin usage and manufacturers by OBD‐II standards

Though many standards are used, there are parts available that convert the signal into a serial binary in RS‐232 standard. Specifically ELM electronics produces a chip that automatically senses the standard being used based on pin activity. Using this method would result in a processed binary signal.

The OBD‐II standard, also meets the sensing criteria. Engine RPM measurement is uniformly supported across all OBD‐II platforms and with the support of a chip like the ELM327, RPM can be read out of cars made since 1996. The OBD‐II port in a car is located in the cab, typically under the steering column. While the port’s location is not common knowledge it is easily accessible and requires little automotive knowledge.

## Others

Several methods of sensing failed to meet the previously stated criteria. At the onset of the project, we sought to measure vehicle RPM by measuring the radio noise generated by sparkplug firing. This method did not meet the universality requirement. Sparkplug manufacturers have worked to decrease this noise. Low noise sparkplugs, previously found mainly in areas where radio was critical, for example nautical engines, are now found in a large number of automobiles as well. There is no way of knowing if this method will work with a given car, without knowing whether or not a user has a low noise sparkplug.

Directly sensing the current across the spark plug would most accurately determine vehicle RPM, but would require the user to have automotive knowledge and the ability to install devices directly to the engine. The same issue arises with conventional tachometer set‐ups, which involve counting flywheel passes. Requiring the user to work in the engine area limits the number of people who could use our device, due to insufficient automotive experience.

# Processing RPM

## Car Adapter Plug

The signal from the adapter plug shows periodic noise at about the 14 V DC point. Figure 5, Figure 6 and Figure 7 show that the noise frequency increases as the RPM increases. The signal also has high frequency noise and transients that need to be processed out.

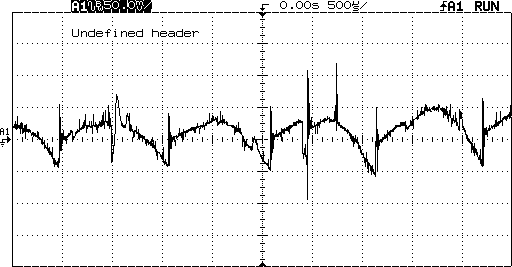


Figure 5: Unprocessed Adapter Plug Signal at 500 RPM (engine idle)

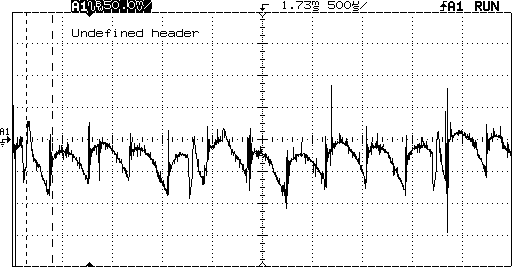


Figure 6: Unprocessed Adapter Plug Signal at 1500 RP

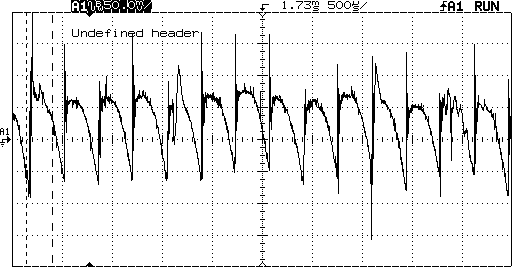


Figure 7: Unprocessed Adapter Plug Signal at 2000 RPM

The signal processing is outlined in Figure 8. First, the 14 Volt DC component is subtracted away. The high‐frequency noise, in this case, anything about 8kHz should be filtered out with a low‐pass filter. Additionally, a band‐pass filter then amplifies the useful range of frequencies, in this case 500 Hz to 4 kHz. A frequency to voltage

converter then processes the signal of varying frequencies into an analog voltage. The voltage can then be converted into a digital value with an A/D converter.

Band Pass Filter

.8‐4 kHz

A/D converter

Freq to Volt Converter Ex LM331; LM2917

Low‐pass Filter

Subtract 14V DC

Adapter Plug Signal

Figure 8: Block Diagram of Adapter Plug Processing

## OBD­II Connector

Elm Electronics provides software to interface between the ELM 327 and a computer, but in order to facilitate an eventual move to a dedicated hardware system; we sought a more direct communication approach. We were able to establish a hyper‐ terminal connection through a serial port with the following settings: 38400 baud, 8 data bits, no parity, xon/xoff flow control. The communication protocol for both the send and receive side is given in Table 2.

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Terminal End to OBD-II Port** | | | | | | | | |
| **Byte #** | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| **Data Carried** | #of add. bytes | Mode | PID | n/u | n/u | n/u | n/u | n/u |
| **Value** | 2 | 01 | 0c | x | x | x | x | x |
| **OBD-II Port to Terminal** | | | | | | | | |
| **Byte #** | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| **Data Carried** | #of add.  bytes | Mode | PID | A  formula | B  formula | n/u | n/u | n/u |
| Value | 3 | 41 | 0c | variable | variable | x | x | x |

Table 2: Serial Communication Protocol Between OBD‐II and Terminal

For example, sending the string 0x010c specifies the fetch current mode (0x01) and the parameter identification number (PID) for RPM (0x0c). The return value is a 4 digit hex number. Because the resolution of the OBD measurement is of .25 RPM, the return value corresponds to four times the instantaneous RPM. A return value of 0x1770 corresponds to the decimal value 6000 and an RPM of 1500.

# Sound Synthesis

Assuming there is a digital signal provided that gives the RPM readout of a car; there is the task of creating a new sound to overlap the current sound of the car. We had to find audio clips of engine sounds to other cars. However, in order to provide a realistic experience, the sound needed to be a full range sound, meaning that the sound must encompass the car’s startup, up shifts, and downshifts.

After we found a car engine sound, we separated the sound into each gear and each RPM so that regardless what RPM is read in; there was a corresponding sound to

match. To prevent the sound from being choppy when the car is accelerating, the right number of audio clips had to be taken. When all this came together, the synchronization of the new car engine sound with the RPM input signal would create a new driving experience.

## Criteria:

The sound synthesis of the project had several criteria because reproducing the harmonious sound of a super car was the entire basis of our project. The greatest challenge with sound synthesis was producing smooth and continuous sound. Testing had to be done to find the right number of sound clips so that all RPM could be synchronized, while creating a smooth and uninterrupted sound. Secondly, there could not be a large number of sound clips otherwise it would take too much memory to store as well as processing power to synchronize.

## Design Choices

Due to issues with consistency and stability we chose to pursue using the ODB‐II connector for reading out RPM. The cigarette lighter did provide useable results, however modern cars aim to filter out the noise in which we needed for the project.

Therefore, depending on the model of the car, the car’s wiring, as well as the battery connections, results would vary. For these reasons the OBD‐II connector was the preferred method of reading out RPM values.

The OBD‐II connector was capable of reading out RPM values as hex‐values which in‐turn were used in correction with several sound files to piece together the sound of a high performance engine. Our research trials showed that synthesizing the sounds of a vehicle’s acceleration was markedly more difficult than for a steady speed. When a vehicle accelerates there are many sound variations within each gear. Also the sound of acceleration in different gears differs as well. When the car is idling in a steady‐ state however, only one or two sound files are necessary to replicate the sound.

During accelerations through the gears, several sound clips needed to be pieced together to reproduce an accurate and clear sound. It was found that approximately 12 sound clips were necessary to reproduce a clean sound. The 12 audio clips were taken at every 500 RPM intervals. 12 clips were necessary because in general cars idle at about 0.5‐1.0k RPM, and usually have redline limits at approximately 7k RPM. Therefore, beginning at 1k RPM and taking sounds clips at every half interval provided a clean sound throughout the acceleration of any given gear. If the sound were split into 24 clips the sound would be slightly better, but not significant enough to warrant the extra complications associated with additional audio files.

Sound files were taken from BMW because their website provided a full range of sound for several of their vehicles. Using the sound clips provided from (www.bmwusa.com) we used audio editing software called Audacity. Audacity allowed us to trim the sound files into individual gears and RPM.

## Memory

The 12 sound files amounted to approximately 400kb of memory, therefore there should be no problems storing the audio files in a practical application. Our device would need a flash memory module built in with no more than 1GB of memory to be able to store several audio clips from various vehicles. Given the low cost of flash memory chips, especially ones that are only 1GB in capacity, memory costs should not be an issue.

## Audio Output

Delivering the audio clips to the car would be accomplished via several methods.

For our design we examined several possibilities including using an FM‐tuner, line‐in auxiliary cable, or have a built in speaker. While a built in speaker would probably be the simplest application for the user, it would not provide the best auditory experience. For our final design we agreed upon using a FM‐tuner because the vast majority of vehicles on the road today have at least an AM/FM radio. However, not all cars on the road today have an auxiliary input port built in. The downside to using an FM‐tuner is that the sound quality is only average and it requires an additional setup step for users.

However, an FM‐tuner would provide the best balance between sound quality and universality among cars.

# Ethical and Safety Concerns

Engineers are always faced with ethical decisions and concerns whenever they design or build something that is meant to affect numbers of people. Our plug‐and‐play engine sound replicator is no exception in that there are several ethical decisions and concerns.

The first ethnical concern related to our project is our car engine sounds from several different manufacturers. For the purpose of this project, I downloaded BMW sound files from their website without seeking extensive legal consent. BMW may have no issues either with our use of the sound files for research purposes. However, once a product is developed and intended for sale, there could be legal licensing and trademark issues involved. A car’s engine sound is just as unique as its body style and performance, therefore proper licensing would need to be sought out in order for us to use different car engine sounds in our final product.

Legal concerns are one side of ethical concerns related to our design project; however there are safety concerns as well. The OBD‐II connector port on a car is a diagnosis port with the ability to monitor and edit many car values and functions.

Improper use or untrained individuals could create problems with the electrical systems in a car such as: air‐bag deployment, engine software, braking systems, and cruise control systems. Our device would need to be designed to prevent users from being able to access or change vehicle values both intentionally and unintentionally for their own safety.

A further concern with the OBD‐II connection is that it is a diagnosis port, and not a standard input/output port designed for extensive use. Our device would put tremendous strain on a port that was designed primarily to take diagnostic read outs. While this has not yet been proven to be a safety issue in terms of reliability, it is still a factor that must be taken into consideration.

On the safety side, the OBD‐II port us usually located on the steering column where the driver’s legs may become entangled with the cord, as was experienced during experimentation. For this system to be safe, we would have to devise a way of securing the cord away from the driver’s feet.

One final ethical concern that must be taken into consideration is the fact that producing any type of audio sound whether it is music or engines sounds; will distract drivers in some form or another. There are groups who argue against the use of cell phones and listening to music in cars because they pose a degree of danger. Creating engine sounds of performance vehicles may enrich ones driving pleasure; however, it can also be seen as a dangerous distraction.

# Future Considerations

In the future, there are several ways this project could be expanded upon. There are areas of simplicity that could be further developed. Currently our model requires some sort of portable laptop to read in RPM values as well as synchronize sound files. Needing a computer in the car is not very practical and, in the future, we could improve upon the project by integrating some form of processing unit into the device.

Using the OBD‐II connector to read out RPM values requires a cable to be running from underneath the steering column across the car. Also the device requires to be plugged into the cigarette lighter for power. In the future, we could explore the use of wireless technology to remove the OBD‐II cable running across the vehicle. Also, research could be done in implementing a battery in our device that way it would not need to be plugged in. Because our project is still in its preliminary design stages, many fine details had to be over looked. In the future we would work to address all the tiny details and improve the ease of use for the customer.

# Conclusions

Our goal with this project was to create a product to bring super car engine sounds to everyday cars. Using an OBD‐II connector and properly edited sound files, people can experience driving a super car for a fraction of the cost. The main costs of our design would be the OBD‐II cable, a processing chip, and memory for the sound files. Despite these costs, they would not amount to as much time and money that would be required to mechanically replace one’s engine exhaust at an automobile repair shop.

There are still legal and ethical issues which need to be addressed, however even with these set‐backs there is a great potential in our product being successful. From an engineering perspective, we were able to get our model working smoothly and consistently. Given a greater amount of time to fine‐tune and perfect our model, it would not be difficult to produce a product that would be easy to use and relatively inexpensive.